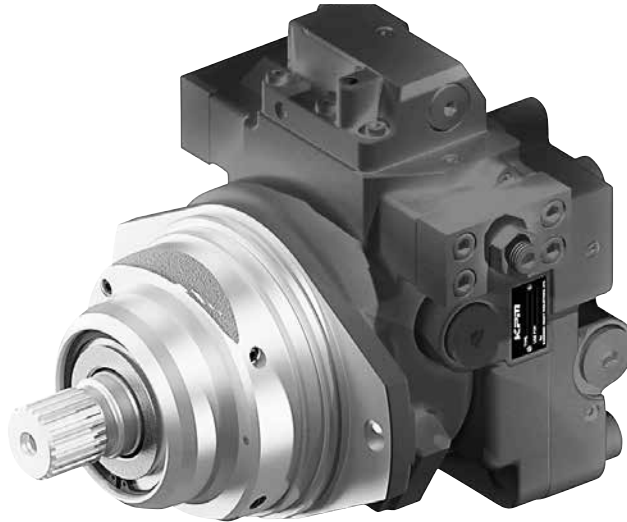


## Variable Displacement Type Axial Piston Motors (Cartridge type)



### ■ Specifications

Size : 160

Nominal Pressure : 42MPa (6,090 psi)

Maximum Pressure : 50MPa (7,250 psi)

### ■ General Descriptions

- Applicable to an open circuit and closed circuit.
- Applicable to construction machinery and industrial vehicles.
- Swash plate design allows for a compact motor.
- High power density.

### ■ Features

#### **Superior performance at High and Low speed**

Optimized rotary balance design enables high speed performance and excellent low speed characteristics.

#### **Low noise**

Swash plate configuration provides the low noise.

#### **Compact size**

Swash plate configuration provides the more compact structure and flexibility in system design.

#### **Long bearing life**

Swash plate configuration results in longer bearing life.

#### **Cartridge type**

Space saving configuration, easy to install into the gearbox.

# 5

## M7VC Ordering Code

Model Code **M7VC 160 A C 4 7 - A A 1 T1 X X X N - 01**

### 1. M7VC Series

M7VC Series, Variable Displacement, Axial Piston Motor, Cartridge Type, Applicable in Both Open and Closed Loops.

### 2. Size

	160
Standard Size	●

### 3. Series Specifications

A	Standard
---	----------

### 4. Mounting Flange and Port Position\*

	Mounting	Port Position	160
C		Rear	●
D	φ 200(φ 250 - 2 bolt mount)	Side	○
E		Bottom	○

### 5. Port and Flange Fixing Thread\*

	Type of Threaded Port	Thread Type for Flange Port	160
1	ANSI ISO11926	ANSI ASME B1.1	○
4	Parallel Piping ISO228	Metric ISO724	●

### 6. Shaft End\*

	Standard	Specifications	160
2	ANSI B92.1	1 3/4 in 13T 8/16DP	○
3	ANSI B92.1	2 in 15T 8/16DP	○
7	DIN 5480	W45x2x21x9 g	●
8	DIN 5480	W50x2x24x9 g	●

\*Following combination of code [5], [6] is available.

	Ordering Code	
	Code[5]	Code[6]
M7VC160	1	2 or 3
	4	7 or 8

● : Available  
○ : Under development  
— : Not available

# 5. M7VC Ordering Code

Model Code <sup>1</sup>M <sup>2</sup>7 <sup>3</sup>V <sup>4</sup>C <sup>5</sup>1 <sup>6</sup>6 <sup>7</sup>0 - <sup>8</sup>A <sup>9</sup>A <sup>10</sup>1 <sup>11</sup>T <sup>12</sup>X <sup>13</sup>X <sup>14</sup>X <sup>15</sup>N - 01

### 7. Maximum Displacement

Size	160	A : 160	●	B : 155	●	C : 150	●	D : 140	●
------	-----	---------	---	---------	---	---------	---	---------	---

### 8. Minimum Displacement

Size	160	A : 96	●	B : 80	●	C : 60	●	D : 40	●	E : 32	●
------	-----	--------	---	--------	---	--------	---	--------	---	--------	---

### 9. Speed Sensor

		160
1	w/o Speed Sensor	●
2	w/ Speed Sensor	●

○For code [10] [11] please refer to page 57.

### 12. Accessories

	Flushing Valve	Internal Cooling	Flushing Flow	160
X	w/o Flushing Valve	w/ Internal Cooling	5.0 L/min (M7VC160) at ΔP(Lower Pressure - Drain Pressure)= 2.5MPa and v =10mm <sup>2</sup> /s	●
1	w/o Flushing Valve	w/o Internal Cooling	—	●
2	w/ Flushing Valve	w/ Internal Cooling	5.0 L/min (M7VC160) at ΔP(Lower Pressure - Drain Pressure)= 2.5MPa and v =10mm <sup>2</sup> /s	○

### 13. Counter Balance Valve

		160
X	w/o Counter Balance Valve	●
1	w/ Counter Balance Valve Hoist at CW Rotation (A port inlet)	○
2	w/ Counter Balance Valve Hoist at CCW Rotation (B port inlet)	○

### 14. Response Speed of Control

		160
N	Standard	●

### 15. Design Code

		160
**	01~	●

● : Available  
○ : Under development  
— : Not available

# 5. M7VC Ordering Code

Model Code **M7VC 160 A C 4 7 - A A 1 T1 X X X N - 01**

### 10.Regulator(See the table on possible combinations of optional valve and regulator options.)

			160	
T	T1	Electric Two Position Displacement Control	Negative Control, 24V	●
	T2		Negative Control, 12V	●
Y	Y1	Hydraulic Two Position Displacement Control	Negative Control	●
	Y2		Positive Control	●
E	E1	Electric Proportional Control	Negative Control, 24V	●
	E2		Positive Control, 24V	●
	E3		Negative Control, 12V	●
	E4		Positive Control, 12V	●
P	P1	Hydraulic Proportional Control	Negative Control, Pi = 2.5MPa	●
	P2		Positive Control, Pi = 2.5MPa	●
	P3		Negative Control, Pi = 1.0MPa	●
	P4		Positive Control, Pi = 1.0MPa	●
H	H1	Pressure Related Control	w/o Pressure Increase	●
	H2		w/ Pressure Increase	●
	H3		w/ Pressure Increase and Hydraulic Remote Control	●

### 11. Options for Optional Valves (See the table on possible combinations of optional valve and regulator options.)

			160	
X	w/o Any Optional Valve		●	
A1	Pressure Control Valve	w/ a Pressure Control Valve	●	
B	B1 B2	Electric Two Position Control Valve	w/ Electric Two Position Control Valve, 24V	●
			w/ Electric Two Position Control Valve, 12V	●
C	C1 C2	Hydraulic Two Position Control Valve	w/ Hydraulic Two Position Control Valve, Negative Control	●
			w/ Hydraulic Two Position Control Valve, Positive Control	●

### ★ M7V Control Options

Note: The control options are common for all motor sizes.

			Options for Optional Valves (code [11])					
			w/o Any Optional Valve	w/ a Pressure Control Valve	w/ Electric Two Position Control Valve, 24V	w/ Electric Two Position Control Valve, 12V	w/ Hydraulic Two Position Control Valve, Negative Control	w/ Hydraulic Two Position Control Valve, Positive Control
Regulator : Code [10]			X	A1	B1	B2	C1	C2
T	T1	Electric Two Position Displacement Control	Negative Control, 24V	●	—	—	—	—
	T2		Negative Control, 12V	●	—	—	—	—
Y	Y1	Hydraulic Two Position Displacement Control	Negative Control	●	—	—	—	—
	Y2		Positive Control	●	—	—	—	—
E	E1	Electric Proportional Control	Negative Control, 24V	●	●	—	—	—
	E2		Positive Control, 24V	●	○	—	—	—
	E3		Negative Control, 12V	●	●	—	—	—
	E4		Positive Control, 12V	●	○	—	—	—
P	P1	Hydraulic Proportional Control	Negative Control (Pi = 2.5MPa)	●	●	—	—	—
	P2		Positive Control (Pi = 2.5MPa)	●	○	—	—	—
	P3		Negative Control (Pi = 1.0MPa)	●	●	—	—	—
	P4		Positive Control (Pi = 1.0MPa)	●	○	—	—	—
H	H1	Pressure Related Control	w/o Pressure Increase	●	—	●	●	●
	H2		w/ Pressure Increase	●	—	●	●	●
	H3		w/ Pressure Increase and Hydraulic Remote Control	●	—	●	●	●

(Note)

For combination of two position control and pressure cut-off control, please select the pressure related control (code H) with two position control as option valve.

- : Available
- : Under development
- : Not available

# 6

## Technical Information

### 6-1 Specifications

#### M7VC Series

Size		160
Min. Displacement : $q_{min}$	cm <sup>3</sup> (in <sup>3</sup> )	0 to 128 (0 to 7.9)
Max. Displacement : $q_{max}$	cm <sup>3</sup> (in <sup>3</sup> )	128 to 160 (7.9 to 9.8)
Max. Speed : $N_{nom} / N_{max}^{*1}$	min <sup>-1</sup> (rpm)	3,100 / 4,900
Nominal pressure : $P_{nom}^{*2}$	MPa (psi)	42 (6,090)
Max. Pressure : $P_{max}$	MPa (psi)	50 (7,250)
Theoretical output torque	Nm (lbf ft)	1,070 (789)
Power	kW (hp)	347 (465)
Max. Flow : Q	L/min (gallon/min)	496 (131)
Moment of inertia	kg·m <sup>2</sup>	0.030
Volume in the case	L (gallon)	2.5 (0.66)
Mass	kg (lb)	72 (158)
Temperature	°C (°F)	-20 to +115 (-4 to +239) at drain port -20 to +90 (-4 to +194) at inlet port
Coating		Red synthetic resin primer

Values shown in the table above are theoretical values.

\* 1 :  $N_{nom}$  : Max. speed at  $q_{max}$ .

$N_{max}$  : Max. speed at  $q < 0.6q_{max}$ .

(In case that 1 is selected at ordering code [12],  $N_{max}$  goes down up to  $N_{nom}$  regardless of displacement of the motor.)

\* 2 : Nominal pressure corresponds to the design pressure to provide proper performance, function, and service life.

## 6. Technical Information

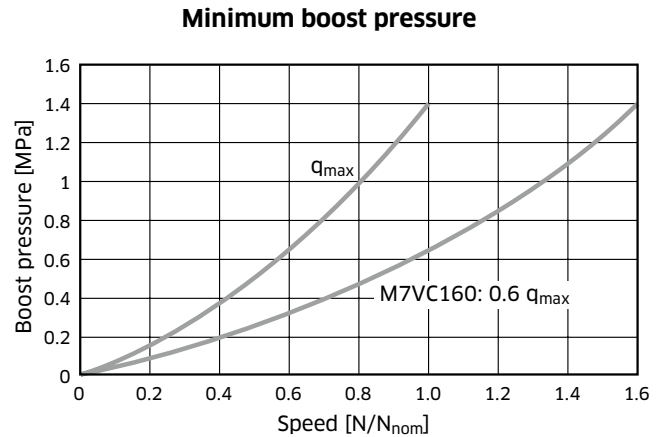
# 6-2 Precautions for System Design

### M7VC series

#### ◆ Minimum Boost Pressure

To prevent cavitation when the motor is operating in a pumping mode, a positive pressure is required at the suction port.

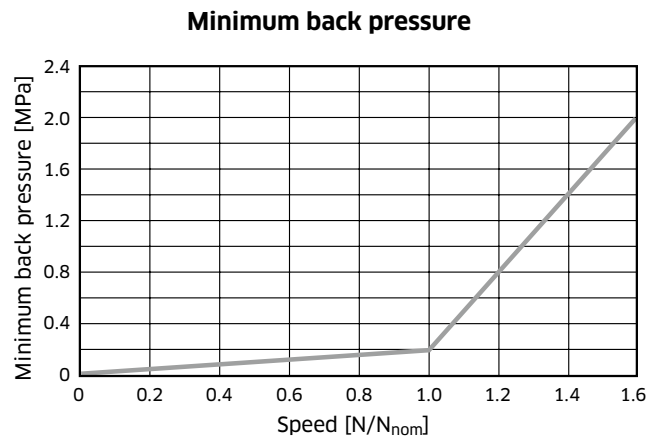
The figure on the right shows the minimum boost pressure requirement based on the regular operation. In case of a rapid change of the flow volume, more boost pressure must be applied.



#### ◆ Minimum Back Pressure

To ensure the optimal performance and life time the back pressure is required at the lower pressure port.

Motor casing pressure must be  $\leq 0.2$  MPa.

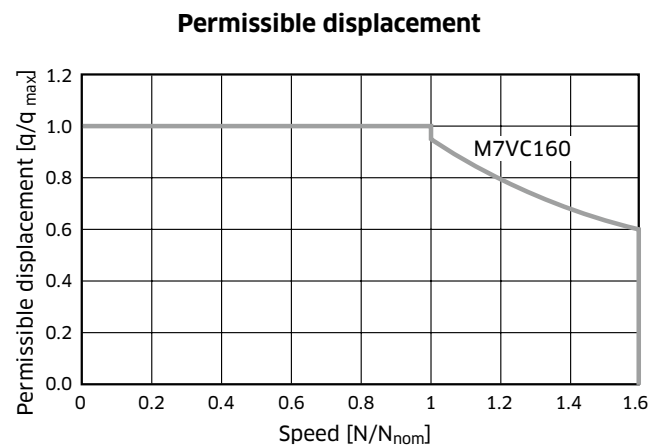


#### ◆ Permissible Displacement, Speed Related

The figure on the right shows permissible displacement in relation to the motor operating speed. Design the system not to exceed this requirement.

#### ◆ Beginning of Control for Winch Device

For the safety reasons, winch device are not permissible with beginning control at  $q_{min}$ .



## 6. Technical Information

### 6-3 Speed Sensor

#### Ordering Code [9] : 1, 2

##### ◆ 1 : w/o Speed Sensor

● A speed sensor is not installed.

##### ◆ 2 : w/ Speed Sensor

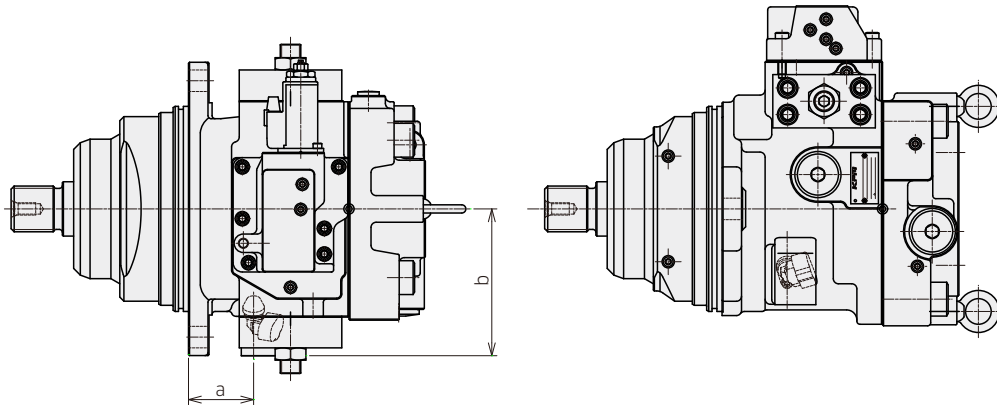
● A speed sensor that detects the motor direction and measures the rotational speed of the motor is installed at the position as below figure.

#### Specification

Supply Voltage : 4.5V ~ 26V DC

Mating Connector : TE Connectivity AMP Superseal 1.5 series, 4 positions(part number : 282088)

IP Protection Rating : IP69K



	M7VC160
a [mm]	63.5
b [mm]	143
Pulse Frequency [pulse/rev]	87

# 7

# Dimensions

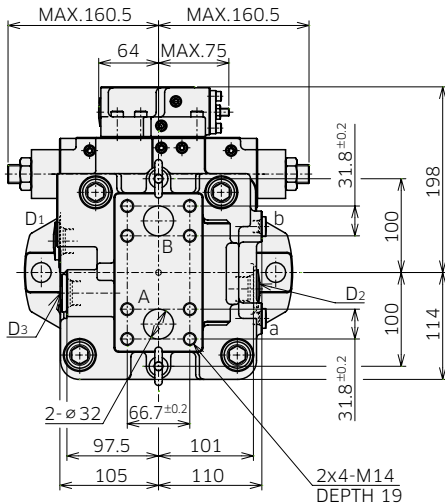
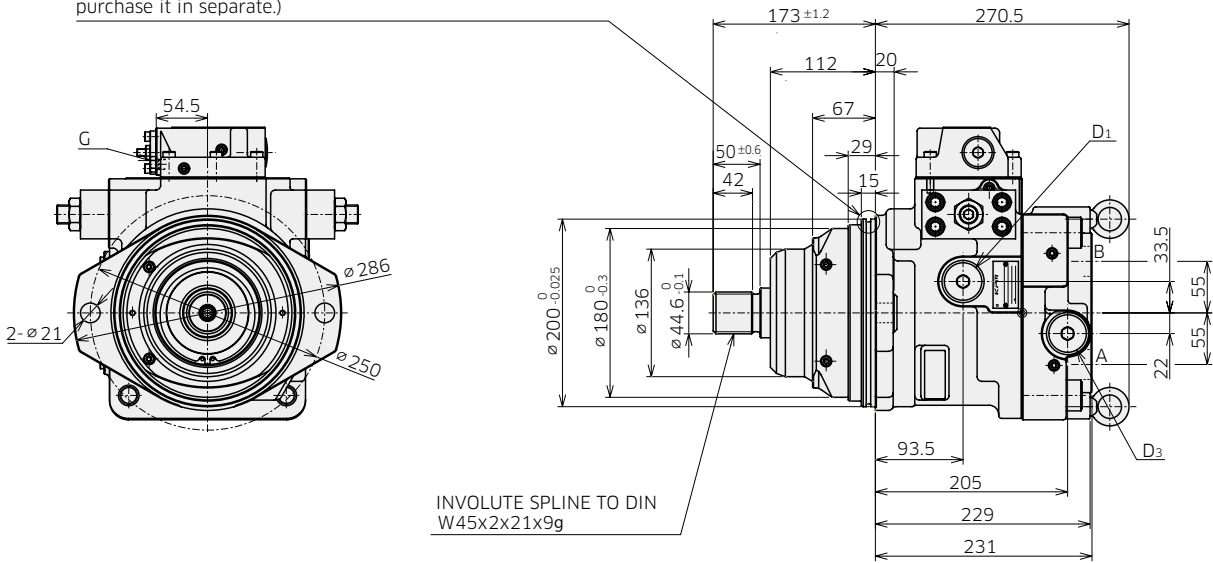
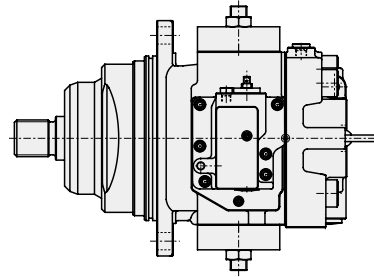
## 7-1 Installation Dimensions

\* Dimensions in mm.

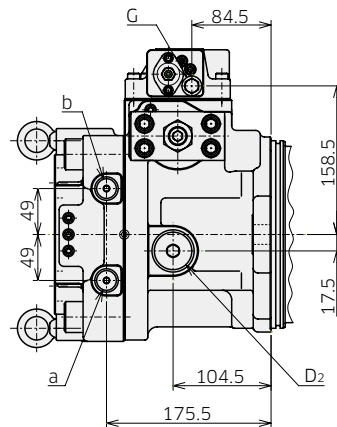
### ◆ M7VC160, Rear Port

Model Code : M7VC 160 A C 4 Z - \* \* \* \* \* \* \*

O-ring size: 190.09×3.53  
 Kawasaki part number : 00RWG42 (SAE standard: AS568-264)  
 (The O-ring is not included in the scope of delivery. Please purchase it in separate.)



↑ W



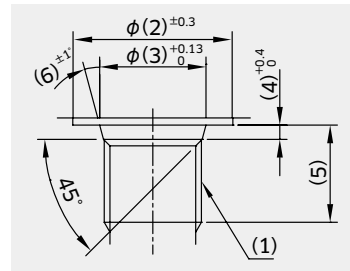
Refer to the page 63 and 64 for dimensions with other regulator options.



## 7. Dimensions

### 7-1 Installation Dimensions

#### ◆ M7VC160 Port and Flange Fixing Thread (Ordering code [5]) Thread Port



\* Dimensions in mm.

ANSI thread type (Code : 1)

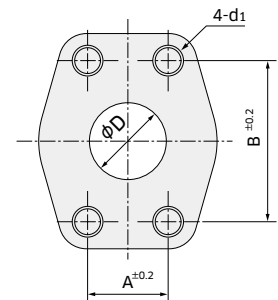
	Symbol	(1)	(2)	(3)	(4)	(5)	(6)	Tightening torque (Nm)
Gauge port	a, b	9/16-18UNF-2B	25	15.6	2.5	12.7	12	59
Gauge port	G	7/16-20UNF-2B	21	12.4	2.4	11	12	12
Pilot port	Pi	9/16-18UNF-2B	25	15.6	2.5	12.7	12	59
Drain port	D1 to D5	1-1/16-12UN-2B	41	29.2	3.3	16.7	15	170

Parallel piping thread type (Code : 4)

	Symbol	(1)	(2)	(3)	(4)	(5)	(6)	Tightening torque (Nm)
Gauge port	a, b	G 1/4	25	15.6	2.5	15	15	36
Pilot port	Pi	G 1/4	24	15.6	2.5	14	15	36
Drain port	D1 to D5	G 3/4	45	30.8	3.5	16.7	15	170

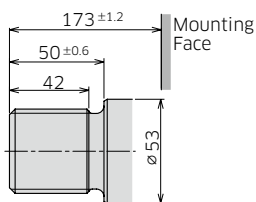
Flange Port

Port thread type code	d1	A	B	D
1	1/2-13UNC-2B	31.8	66.7	32
4	M14	31.8	66.7	32



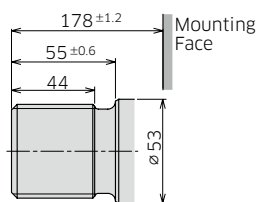
#### ◆ Shaft End (Ordering Code [6])

**DIN 5480**  
(W45x2x21x9g)



Code : 7

**DIN 5480**  
(W50x2x24x9g)



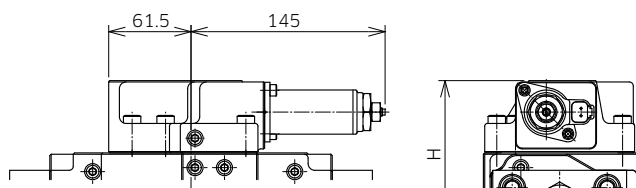
Code : 8

## 7. Dimensions

# 7-2 Regulators Installation Dimensions

\* Dimensions in mm.

### ◆ Electric Two Position Displacement Control Regulator Code: T1, T2

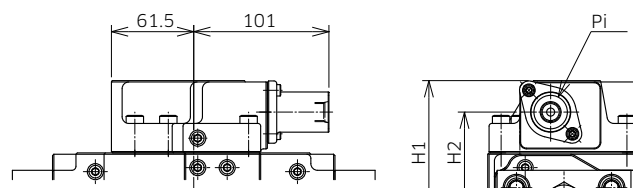


Dimension H : Height from shaft center.

Dimension H (mm)

Motor size	Dimension	
	H	
160	198	

### ◆ Hydraulic Two Position Displacement Control Regulator Code: Y1, Y2



Dimension H : Height from shaft center.

Dimension H1, H2 (mm)

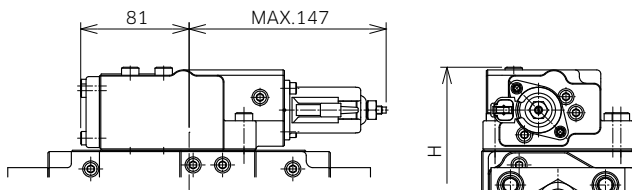
Motor size	Dimension	
	H1	H2
160	198	175

## 7. Dimensions

# 7-2 Regulators Installation Dimensions

\* Dimensions in mm.

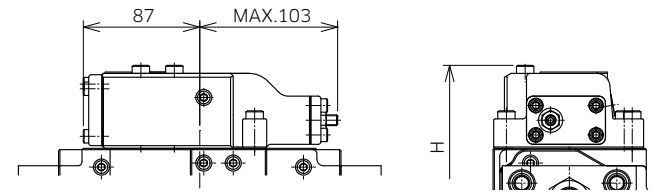
### ◆ Electric Proportional Control Regulator Code: E1, E2, E3 and E4



Dimension H : Height from shaft center.

Dimension H (mm)	
Motor size	Dimension
	H
160	206

### ◆ Pressure Related Control (with Pressure Increase) Regulator Code: H2



Dimension H : Height from shaft center.

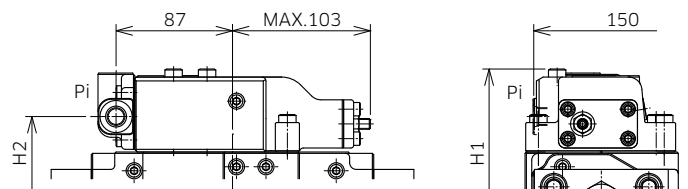
Dimension H (mm)	
Motor size	Dimension
	H
160	206

### ◆ Pressure Related Control (with Pressure Increase Cut-Off Shift) Regulator Code: H3

### ◆ Hydraulic Proportional Control Regulator Code: P1, P2, P3 and P4

Dimension H1, H2 (mm)

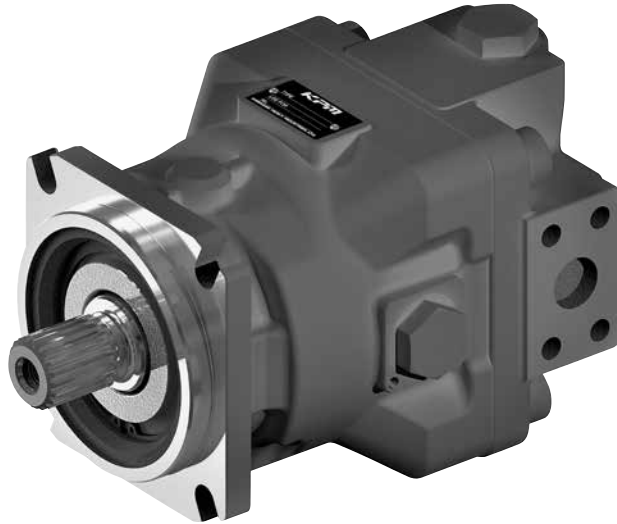
Motor size	Dimension	
	H1	H2
160	206	171



Dimension H : Height from shaft center.

# M7X Series

## Fixed Displacement Type Axial Piston Motors



### ■ Specifications

Size : 85, 112, 160

Nominal Pressure : 42 (6,090 psi)

Maximum Pressure : 50 (7,250 psi)

### ■ General Descriptions

- Applicable to an open circuit and closed circuit.
- Applicable to construction machinery and industrial vehicles.
- Swash plate design allows for a compact motor.
- High power density.

### ■ Features

#### **Superior performance at High and Low speed**

Optimized rotary balance design enables high speed performance and excellent low speed characteristics.

#### **Low noise**

Swash plate configuration provides the low noise.

#### **Compact size**

Swash plate configuration provides the more compact structure and flexibility in system design.

#### **Long bearing life**

Swash plate configuration results in longer bearing life.